



جامعة خليفة
Khalifa University

Introduction to ROS

TUESDAY, JULY 19, 2022



ROS is huge

ROS is an open-source, meta-operating system for robots

What is ROS, When to use it , and Why?




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ROS goals:

- Provide a **standard** for robotic applications
- Use on **any robot**

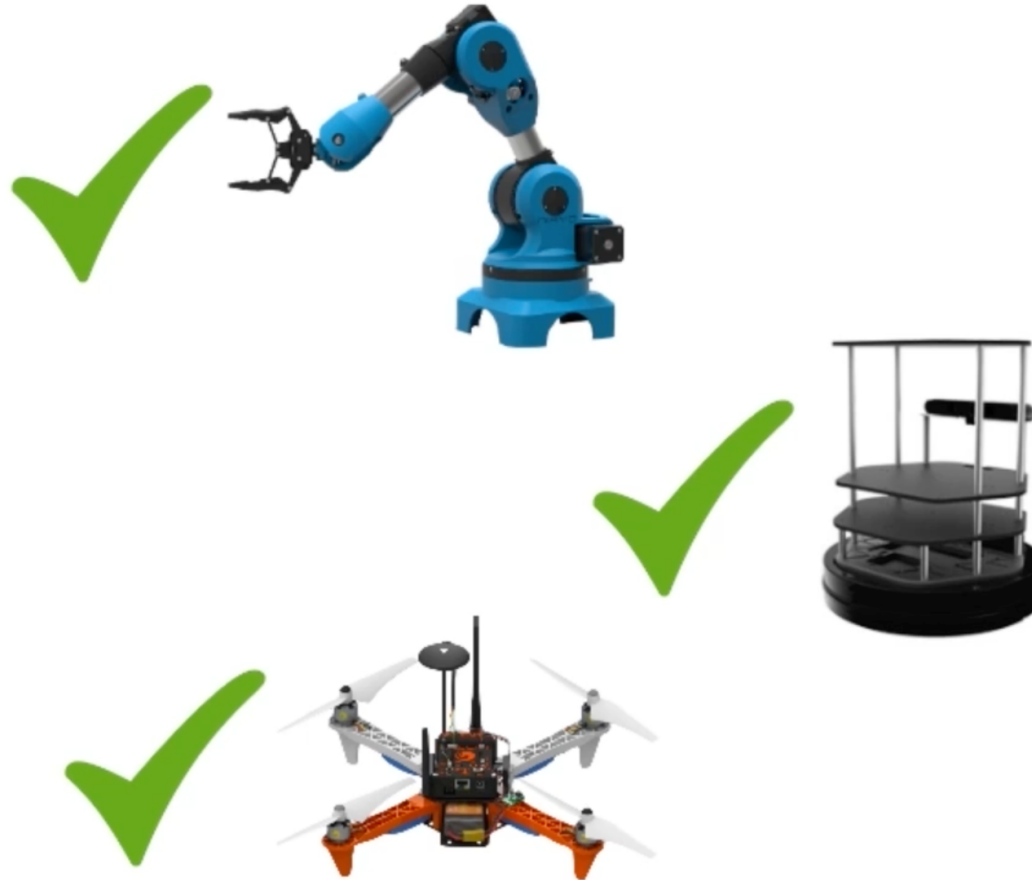
What is ROS, When to use it , and Why?



ROS
Robot Operating System

- Basics
- Core functionalities

→ Program a new robot
in no time !

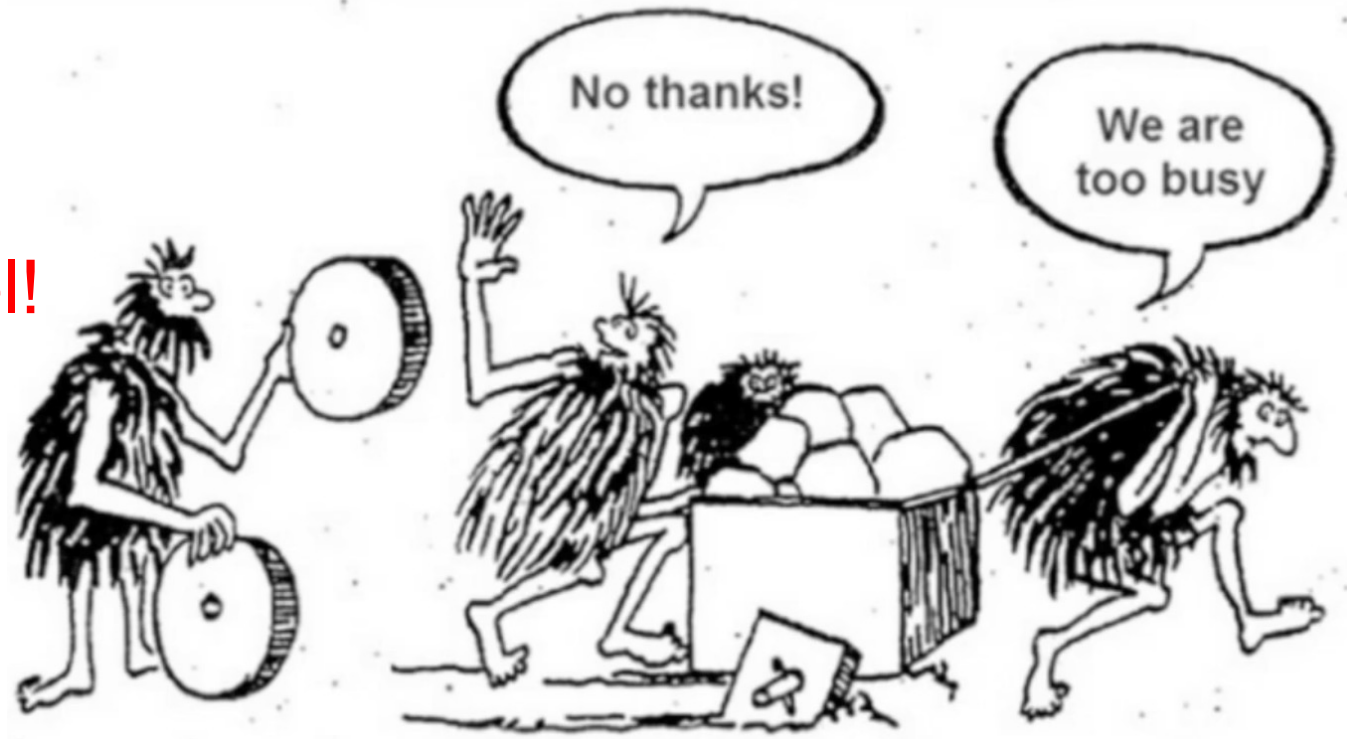


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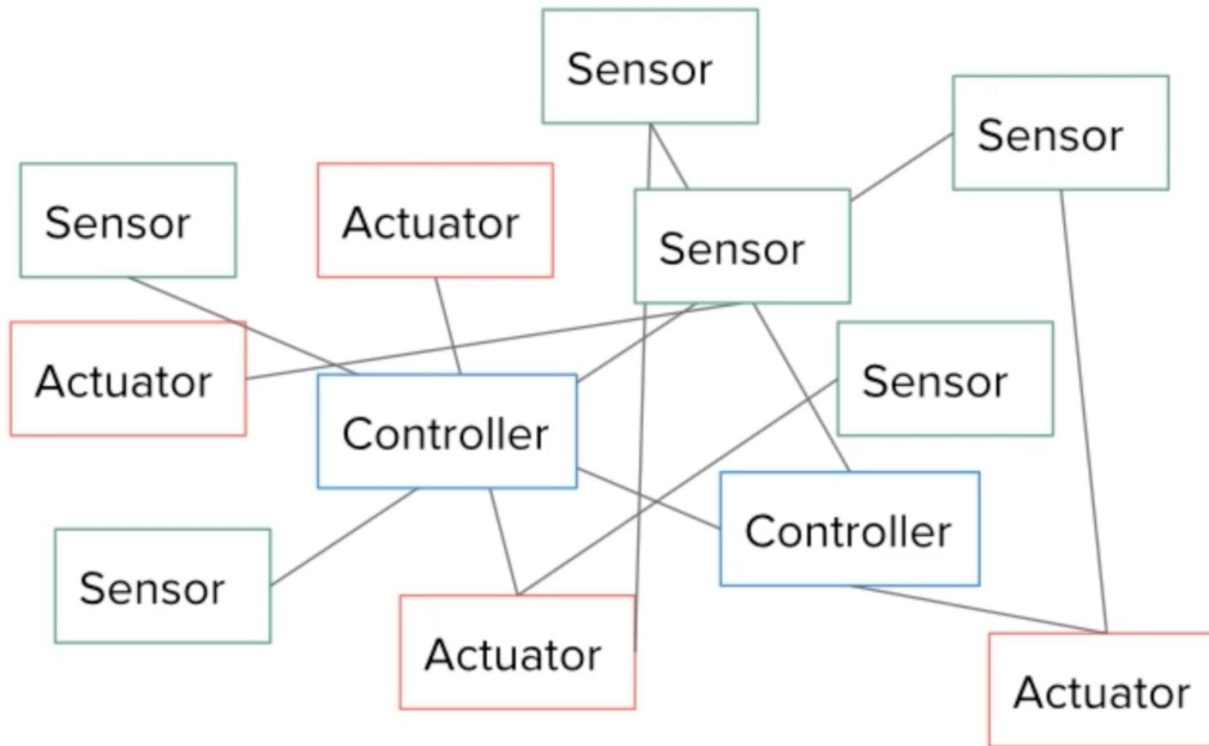
Don't reinvent the wheel!



What is ROS, When to use it , and Why?

When to use ROS ?

What is ROS, When to use it , and Why?



What is ROS, When to use it , and Why?

What is ROS?

What is ROS, When to use it , and Why?

- Code separation and communication tools
- Plug & Play libraries

What is ROS, When to use it , and Why?

Camera



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Motion Planning

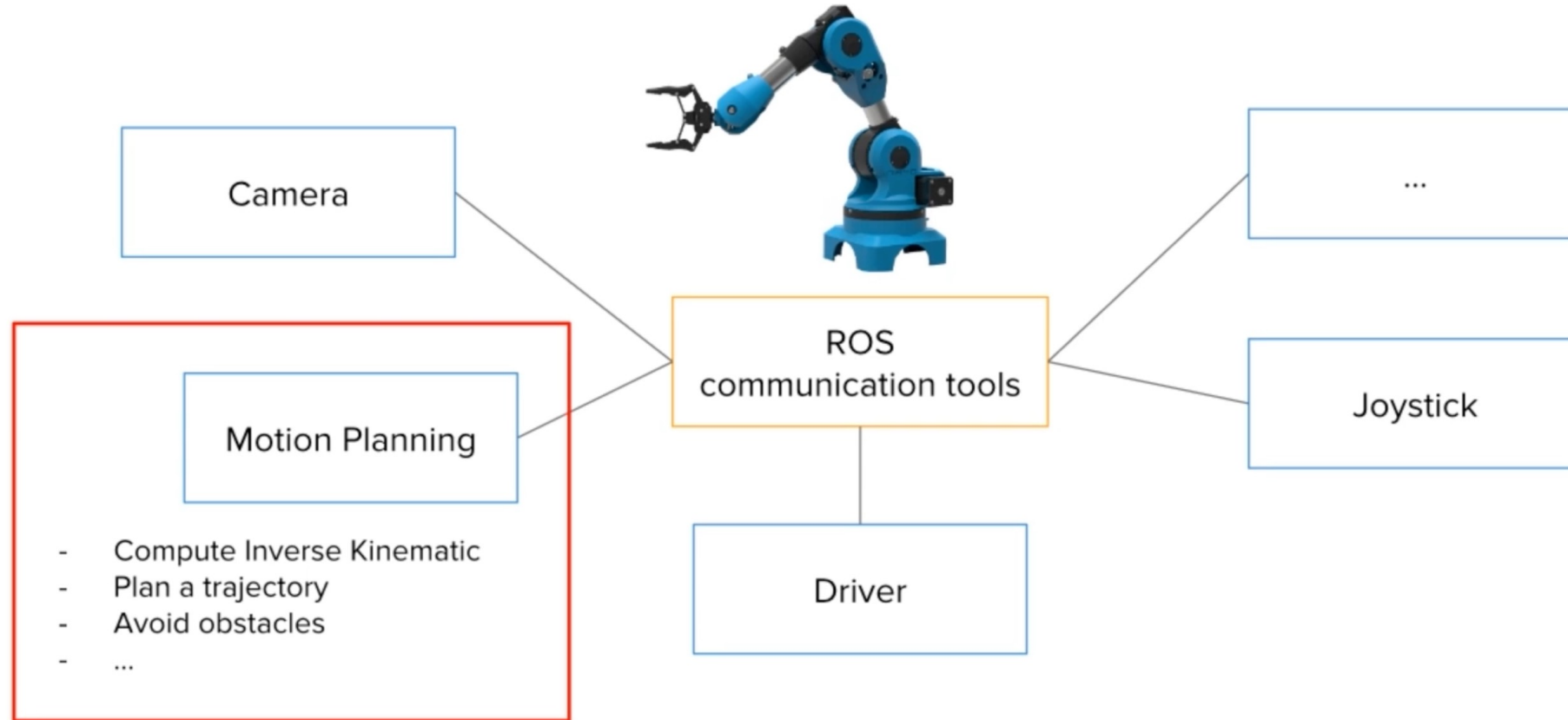
Joystick

Driver

What is ROS, When to use it , and Why?

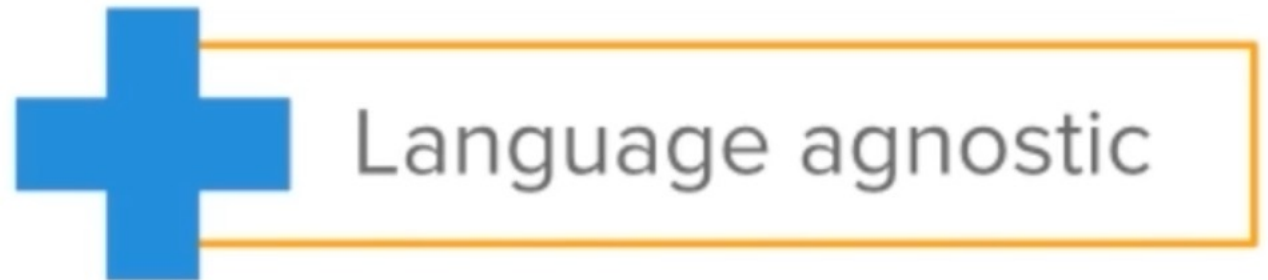
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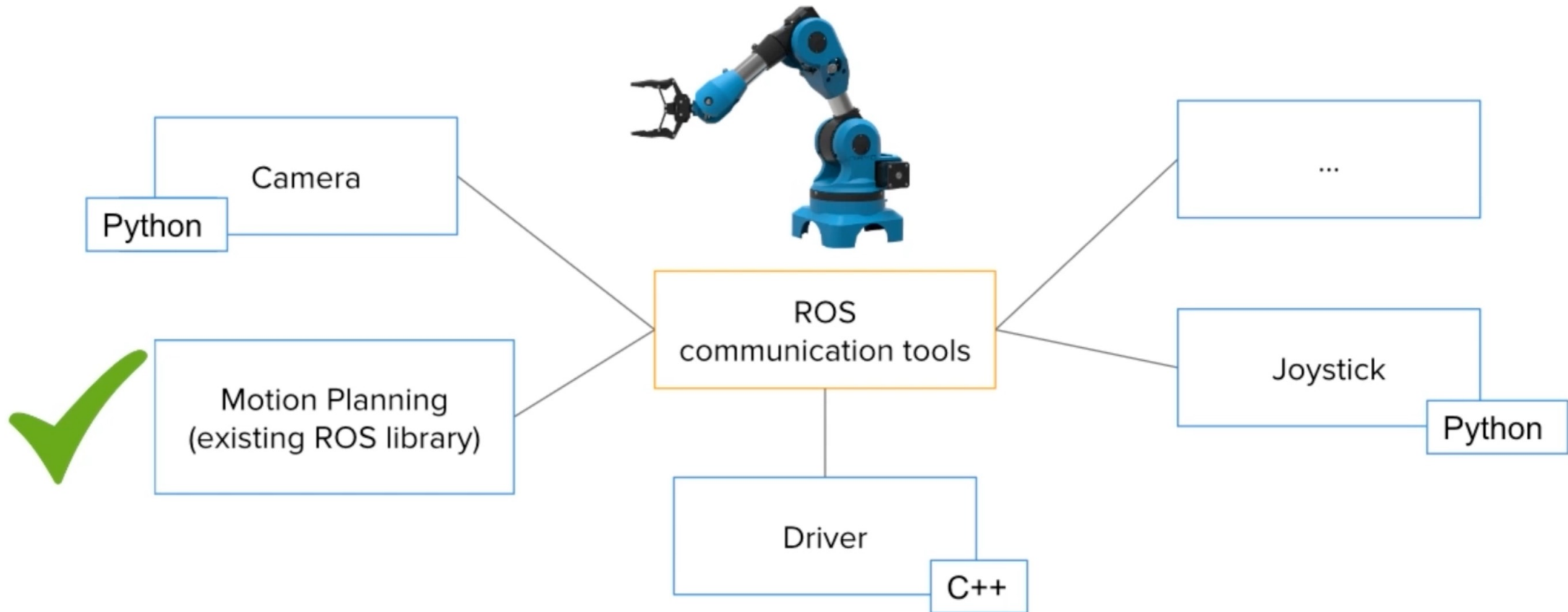


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What is ROS, When to use it , and Why?



What is ROS, When to use it , and Why?

- Open Source
- Active community
 - ❖ Get some help
 - ❖ Share your project
 - ❖ Contribute

